

Malin Space Science Systems

Exploration Through Imaging

ECAM-C50/M50

Color/Monochrome CMOS Camera, Rolling Shutter, 2592x1944, 2.2µm pitch

| Electro-Optical | | |
|---------------------------|--|--|
| Band | Visible | |
| Color Band | M50: Monochrome C50: RGB Bayer Color Filter | |
| Wavelength Range | 350-750 nm (mono) 400-500 nm (blue) 500-575 nm (green) 575-750 nm (red) | |
| Peak QE | >62% at 500nm (mono) | |
| Electronic Shutter Modes | Rolling | |
| Pixels | 5.0 Mpixel | |
| Horizontal Resolution | 2592 pixels | |
| Vertical Resolution | 1944 pixels | |
| Pixel Pitch | 2.2 μm | |
| Array Diagonal | 7.2 mm | |
| Conversion Bit Depth | 12 bit | |
| Temporal Noise | 9 e- | |
| Full Well | 7,000 e- | |
| Dynamic Range | 57.8 dB | |
| Frame Rate, Native Format | 2.8 fps (200 Mbit/s SpW) | |

| Power | |
|----------------|-------------------|
| Supply Voltage | 5V (4.5 to 5.25V) |
| Power, Idle | 1 W |
| Power, Imaging | 1.6 W |

| Thermal | |
|---------------------------|---|
| Operating Temperature | -30 to +40 °C |
| Protoflight Qualification | -40 to +55 °C |
| Non-Operating Temp. | -50 to +70 °C |
| Temperature Sensing | Internal ISL71590 available for readout on J1 |

| Survivability | |
|---------------------------------|--|
| Radiation Design Environment | 5 years GEO (up to 15 years GEO optional) |
| Predicted MTTF | 7.9 million hours |
| NASA TRL | 9 |



ECAM-C50/M50

Features

- Compact and low power
- Standardized ECAM interface

Applications

- Orbital rendezvous and proximity operations (RPO)
- Star navigation
- Natural Feature Tracking (NFT)
- Space Situational Awareness (SSA)

Programmability

- SpaceWire Rate
- Sensor Clock Rate
- Companding Table
- Gain
- Integration
- Offset
- Region of Interest
- Frame Rate
- Row/Column Skipping
- Binning
- Test Patterns

| Optics | | | |
|---------------------------|-------|---------------|------------|
| Effective Focal Length | F/# | FOV (V° x H°) | Bandpass |
| 3.85 mm | F/3.5 | 62 x 80 | 400-700 nm |
| 7.1 mm | F/3.5 | 33 x 44 | 400-700 nm |
| 12.6 mm | F/3.5 | 19 x 25 | 400-700 nm |
| 29.7 mm | F/3.0 | 8 x 11 | 400-700 nm |
| 63 mm | F/3.7 | 4 x 5 | 400-700 nm |

| Digital | |
|--------------------|--|
| Internal Memory | 64 byte SpW Rx FIFO 512 byte SpW Tx FIFO No Frame Buffer |
| Digital Processing | 12 to 8 bpp Companding (Table Lookup) |
| Data Interface | SpaceWire (Single Port) 100 or 200 MBit/s |

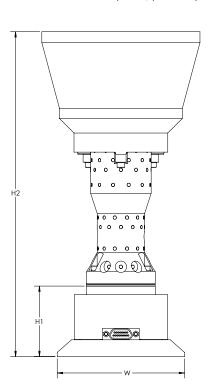


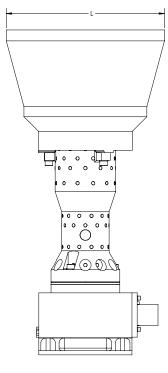
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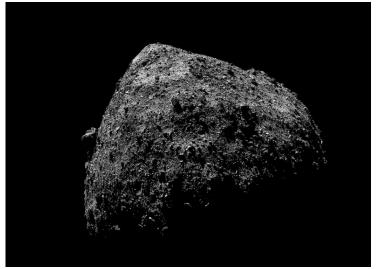
ECAM-C50/M50

Dimensional Envelope, Typical Optics with Baffle





| Mechanical/Interfaces | | | |
|--|---|--|--|
| Mass w/typical optics, & baffle | 590 g | | |
| Dimensional Envelope w/typical optics, & baffle | L: 97 mm W: 78 mm H1: 43 mm H2: 198 mm | | |
| Connectors | J1: Micro-D, 15-Socket ECAM Pinout | | |



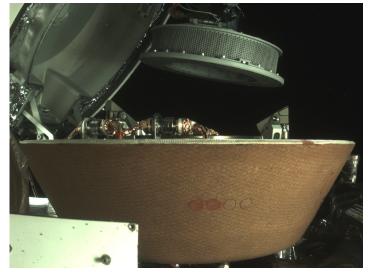
Bennu after Orbital B Insertion

This image was taken from a distance of 690 m above the asteroid's surface by NavCam1 (ECAM-M50), one of three navigation cameras that comprise the spacecraft's TAGCAMS (the Touchand-Go Camera System) suite. At this distance, details as small as 0.5 m across can be resolved in the center of the image. Credit: NASA/Goddard/University of Arizona/Lockheed Martin

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NASA's OSIRIS-REX

This StowCam (ECAM-C50) image shows the collector head hovering over the SRC after the Touch-And-Go Sample Acquisition Mechanism (TAGSAM) arm moved it into the proper position for capture. StowCam, a color imager, is one of three cameras comprising TAGCAMS (the Touch-and-Go Camera System), which is part of OSIRIS-REx's guidance, navigation, and control system. Credit: NASA/Goddard/University of Arizona/Lockheed Martin